

# IDENTIFYING & ESTIMATING BEHIND THE METER PV CAPACITY ON A FEEDER USING MACHINE LEARNING

## Objective

- Lack of precise data on behind the meter photovoltaic (PV) system capacity and output.
- Develop a **machine learning model** that, given a certain geographical location, can **detect the amount of solar panel arrays** and then estimate the **yearly solar power generation**.
- Meet the needs of urban planning and renewable energy sectors, and efficient electrical supply allocation and overall grid stability management.

## System Design and Requirements

### System Design

- Satellite Image and Solar Information Retrieval
- Solar Panel Detection
- Solar Energy Estimation
- Roboflow for annotation
- Segment Anything Model for pseudo label generation

### System Requirements

- Collection and annotation of over 2000 images
- Achieve 85% mAP50 for bounding boxes and 80% mAP50 for masks.
- Fully automated end-to-end process.
- Scalable address processing.
- Generalizable to U.S. addresses.

## Conclusion and Future Work

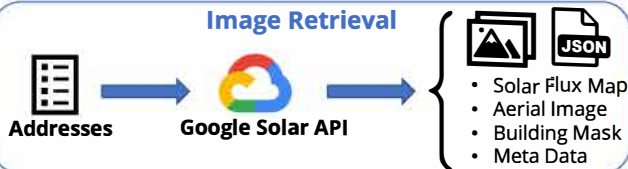
### Conclusion

- Our system demonstrates the feasibility of using a vision-based algorithm to analyze residential solar panels on a large scale.
- System implementation follows intended design with some caveats.

### Limitations and Future Work

- Limited training image dataset
- Lack of fine-grained ground truth data to validate our estimation
- Could analyze feeder data and account for other factors such as precipitation or soiling to improve PV energy estimation.
- Could utilize different APIs (pvlb, pvgis, pvwatts)

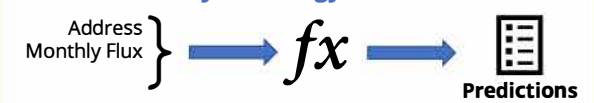
## Image Retrieval



## Solar Panel Detection



## Monthly PV Energy Estimation



## Image Collection, Processing, and Annotation

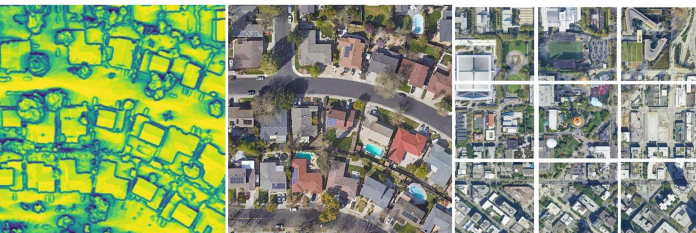


- Learned on 1656 train + 414 validation, 640x615 pixel images [3].
- Sampled addresses from many urban counties across USA to generate training and validation set.



Left: unannotated image with solar panels.  
Right: annotated image with solar panels using square bounding boxes [3].

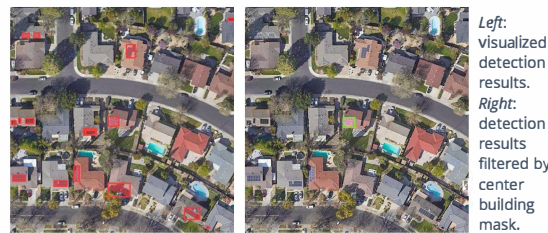
- Used Roboflow to host the dataset, train, run inferences, and annotate images.
- First set of custom dataset images were annotated using square bounding boxes.
- Collects **solar flux** (incident sunlight) map (left), **RGB image** (center), and can automatically do this for a **grid of images** (right).



## Solar Panel Detection

	Train Epoch	Box mAP 50	Box mAP 50-95	Box mAP 50	Mask mAP 50	Mask mAP 50-95
YOLOv8+ BBox	100	<b>0.86</b>	0.65	0.75	0.84	0.47
YOLOv8-seg+ Polygon	100	<b>0.86</b>	<b>0.67</b>	<b>0.77</b>	0.84	0.47

- Detector: Ultralytics YOLOv8-seg [1].
- Instance mask pseudo label generator: Segment Anything Model (SAM) [2].
- Post process detection results by filtering instances with building mask and calculate instance mask area.



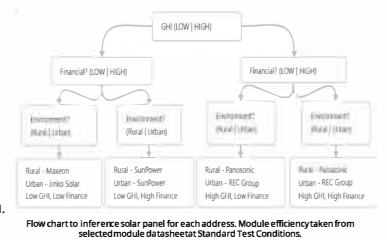
$$\text{System Size} = \text{Array Area} \cdot 1 \frac{\text{W}}{\text{m}^2} \cdot \text{module efficiency}$$

$$E = P_p \cdot r_p \cdot H_{kl}$$

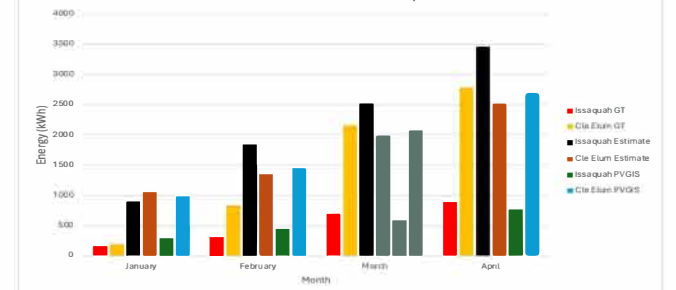
Where:  
 $E$ : is the monthly potential in kWh  
 $P_p$ : Peak power of the system in kW  
 $r_p$ : System losses  
 $H_{kl}$ : Monthly total radiation in kWh/kW/month

Algorithm from similar study done [4].

- Array area is generated from our detection model.
- Peak power is the system size.
- We keep system losses constant at 14% for each ROI.
- Monthly total radiation is taken from flux map layers generated from Google Solar.



## Estimate to Ground Truth Comparison



PVGIS specifications chosen as crystalline-silicon technology, optimal azimuth, optimal array tilt, 14% system losses [5].